This listing of claims will replace all prior listings of claims in the application.

Listing Of Claims:

Claims 1-19 (canceled).

Claim 20 (currently amended): A single lens reflex image sensing

apparatus for capturing an image of object by an image sensing element, comprising:

a battery for supplying electric power;

an operation unit configured to designate a cleaning mode to remove a

foreign substance in a neighborhood of [[and]] or on a photoreceptive surface of the

image sensing element;

a voltage detector configured to detect an output voltage of said battery;

a mirror controller configured to move up/down a mirror;

a cleaning operation allowing unit configured to allow removal of a

cleaning operation for removing the foreign substance by moving up the mirror by said

mirror controller in accordance with designation from said operation unit, in a case where

the output voltage detected by said voltage detector is a first predetermined value or

more;

a warning unit configured to issue a warning in a case where the output

voltage detected by said voltage detector declines to the first predetermined value or less

during the cleaning mode; and

-3 of 10-

1092490 v1

a termination unit configured to move down the mirror using said mirror controller in order to forcefully terminate the cleaning operation, in a case where the output voltage detected by said voltage detector declines to a second predetermined value or less, which is a smaller value than the first predetermined value, during execution of the cleaning mode.

Claim 21 (currently amended): A control method of a single lens reflex image sensing apparatus for capturing an image of object by an image sensing element, comprising:

a step of allowing removal of a cleaning operation for removing a foreign substance by moving up a mirror in a case where an output voltage of a battery is a first predetermined value or more upon designation of a cleaning mode which is provided for cleaning a foreign substance in a neighborhood of [[and]] or on a photoreceptive surface of the image sensing element;

a step of issuing a warning in a case where the output voltage of the battery declines to the first predetermined value or less during the cleaning mode; and

a step of moving down the mirror in order to forcefully terminate the <u>cleaning operation</u> in a case where the output voltage of the battery declines to a second predetermined value or less, which is a smaller value than the first predetermined value, during execution of the cleaning mode.